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(57)Abstract:

SOLUTION: A running pattern production device 1 produced the running pattern of the self-car in a planned running path by using information obtained with a road information obtaining means 11 obtaining information related with the planned running path. By using the information obtained with the road information obtaining means 11, stop times of the self-car in the planned running path is predicted with the stop times prediction means 13 for predicting the stop times of the self-car.

